

## China Starwin OTM45 On The Move Antenna Datasheet



There are different installation methods according to different models. The figure below refers to the SUV model.



Antenna Controller

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#### Introduction:

China Starwin OTM45 0.45m Ku band On-The-Move antenna is an important part of vehicle mounted OTM station, it can maintain accurate and automatic tracking of satellites in the process of vehicle movement, stablishing a continuous and reliable satellite communication connection. The typical application includes the transmission for data, voice and video between satcom OTM station and other fixed stations or mobile stations.

#### Features:

- Light weight, strong adaptation to the vehicle
- Unique heat dissipation design
- Low profile, water droplet shape design
- High gain flat array antenna
- High tracking accuracy, to ensure that the carrier is bumpy, the antenna can stabilize communication.
- Communication distance is unrestricted, deployment flexibility

### **Technical Specifications:**

System Parameter	Тх	Rx
Working Frequency	13.75~14.5 GHz	10.70~12.75 GHz
Antenna Gain	≥33dBi @14.50 GHz	≥32dBi @12.75 GHz
Antenna Type	Flat panel horn array antenna	
Polarization	LP/CP (Can be changed by software)	
Tx/Rx Polarization	According to Modem information, change through software	
Tx Power	≥3W (3W/8W/16W BUC optional),	
	Especially suitable for HTS satellites	
Rx LO.	10.6/9.75GHz (Switching through 22K)	
Tracking Accuracy	≤0.3°	
GPS	Built In	
WiFi	Built In, IEEE 802.11n	
Colour	White (More than 500 units can be customized according	
	to user needs)	
Protection Level	IP66	

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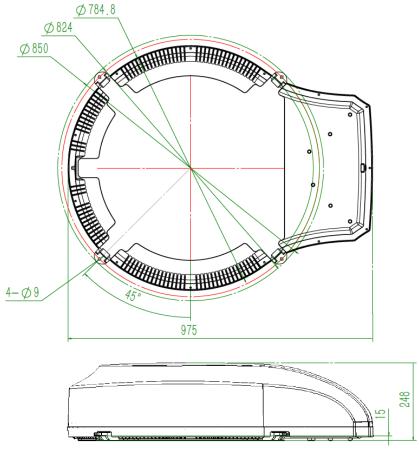
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Stable Mode of Base		Stability of two axes	
Weight		26Kg (Include mounting plate)	
Cover Height		248 mm (Exclude mounting bracket)	
Cover Diameter		975×785mm	
Tracking Performance			
Tracking Mode		Combining inertial measurement with signal tracking	
Capture Time of First Boot		<120s	
Repeat Boot		<30s	
Recapture Time After loss		Instantaneous capture (less than 2S)	
Rotation Range	Azimuth	N×360°Unlimited, continuous	
	Elevation	0~90°	
	Polarization	0~270° (The polarization is controlled by software)	
Tracking Rate	Azimuth	≥100°/s	
	Elevation	≥80°/s	
	Roll	≥80°/s	
Max Angular	Azimuth	800°/s²	
Acceleration	Elevation	600°/s²	
Max Car Body Movement		Max Car Body Movement	
Power Supply			
AC		AC96~265V/50Hz	
DC		DC10~26V	
System Power Consumption		<180W (Average)	
Interface			
Cable Interface		F-Type Connector	
Working Environment Conditions			
Working Temperature		-25°C~55°C	
Relative Humidity		0%~98%	



### **Structural Dimensions**





The outline dimension(L×W×H):  $975 \times 785 \times 248$ mm

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